### Task 5. Systems of linear equations

e-mail: andrzej.kedziorski@fizyka.umk.pl office: 485B http://www.fizyka.umk.pl/~tecumseh/EDU/MNII/

#### Task 5

Write a program that solves a system of linear equations  $\mathbf{A}\mathbf{x} = \mathbf{b}$  with the aid of LU decomposition of  $\mathbf{A}$  matrix. The program gets the number of equations, the elements of  $\mathbf{A}$  matrix and the elements of the right-hand-side column  $\mathbf{b}$  from the input.

### Układ równań liniowych

System of *n* of the linear equations with *unknowns*  $x_i$ , i = 1, ..., n

$$\begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2 \\ \vdots & \vdots & \vdots \\ a_{n1}x_1 + a_{n2}x_2 + \dots + a_{nn}x_n = b_n \end{cases}$$

Matrix form of the system of linear equations

$$Ax = b$$
.

where  ${\bf A}$  is a matrix of factors,  ${\bf x}$  - column of unknowns,  ${\bf b}$  - column of right-hand-sides

$$\mathbf{A} = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix} \quad \mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \qquad \mathbf{b} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix}$$

## Solution of the system of linear equations with triangle matrix

- Consider the system of n linear equations Lx = b, where L is the lower triangle matrix
- ▶ We can solve such system of linear equations with forward-substitution method

$$x_{1} = b_{1}/\ell_{11}$$

$$x_{2} = (b_{2} - \ell_{21}x_{1})/\ell_{22}$$

$$\vdots$$

$$x_{i} = (b_{i} - \sum_{i=1}^{i-1} \ell_{ij}x_{j})/\ell_{ii}$$

:

$$x_n = (b_n - \sum_{i=1}^{n-1} \ell_{nj} x_j) / \ell_{nn}$$

### Solution of the system of linear equations with triangle matrix

- Consider the system of n linear equations Ux = b, where U is the upper triangle matrix
- We can solve such system of linear equations with backward-substitution method

$$x_{n} = b_{n}/u_{nn}$$

$$x_{n-1} = (b_{n-1} - u_{n-1,n}x_{n})/u_{n-1,n-1}$$

$$\vdots$$

$$x_{i} = (b_{i} - \sum_{j=i+1}^{n} u_{ij}x_{j})/u_{ii}$$

$$\vdots$$

$$x_{1} = (b_{1} - \sum_{i=2}^{n} u_{1j}x_{j})/u_{11}$$

# Method of solution of the system of linear equations using LU decomposition

- $\triangleright$  Aim: solve the system of linear equations  $\mathbf{A}\mathbf{x} = \mathbf{b}$
- ▶ We have performed **A** = **LU** decomposition
- Substituting  $\mathbf{LUx} = \mathbf{b}$  and by denoting  $\mathbf{Ux} \equiv \mathbf{y}$ , where  $\mathbf{y}$  is a column  $n \times 1$ , then we have to solve two systems of linear equations with triangle matrices

$$Ly = b$$

and

$$Ux = y$$

with forward- and backward-substitution methods, respectively.

### Inclusion of partial pivoting

Doolittle method with partial pivoting leads to the following decomposition

$$A = LUP$$
.

where permutation matrix **P** is orthogonal, i.e.  $\mathbf{P}^{-1} = \mathbf{P}^{Tr}$ 

Solution of the system of linear equations

$$Ax = b \Rightarrow LUPx = b$$

- 1. Solve Ly = b with forward-substitution method
- 2. Solve  $\mathbf{U}\mathbf{x}' = \mathbf{y}$  with backward-substitution method, where  $\mathbf{x}' = \mathbf{P}\mathbf{x}$
- 3. Solution  $\mathbf{x} = \mathbf{P}^{Tr}\mathbf{x}'$

### Inclusion of partial pivoting

 Metoda Crouta z częściowym wyborem elementu głównego prowadzi do rozkładu

$$A = PLU$$
,

gdzie P jest ortogonalną ( $P^{-1} = P^{Tr}$ ) macierzą permutacji

Rozwiązanie układu równań liniowych

$$Ax = b \Rightarrow PLUx = b$$

- 1. Rozwiązujemy Ly = b' metodą podstawiania wprzód, gdzie  $b' = P^{Tr}b$
- 2. Rozwiązujemy Ux = y metodą podstawiania wstecz



## TO DO - modification of the program with LU decomposition (see Task 4)

- 1. From the input  $^1$  read size n and the elements of  $\mathbf{A}$  matrix
- 2. Perform LU decomposition of **A** matrix using Doolittle or Crout method with partial pivoting
- 3. Solve the system of linear equations  $\mathbf{A}\mathbf{x} = \mathbf{b}$  using LU decomposition of  $\mathbf{A}$  matrix with partial pivoting
- 4. Check  $\mathbf{A}\mathbf{x} = \mathbf{b}$
- 5. Compare the results using existing functions (e.g.  $x = A \setminus b$  in Matlab)

Perform calculations in single precision



#### Examples

$$\mathbf{A}_{1} = \begin{pmatrix} 1 & 1 & 1 \\ 2 & -2 & 2 \\ 3 & 3 & -3 \end{pmatrix} \qquad \mathbf{b}_{1} = \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix}$$

$$\mathbf{A}_{2} = \begin{pmatrix} 1 & 1 & 1 \\ 3 & 3 & -3 \\ 2 & -2 & 2 \end{pmatrix} \qquad \mathbf{b}_{2} = \begin{pmatrix} 3 \\ 1 \\ 2 \end{pmatrix}$$

$$\mathbf{A}_{3} = \begin{pmatrix} 21 & 0 & 770 & 0 & 50666 \\ 0 & 770 & 0 & 50666 & 0 \\ 770 & 0 & 50666 & 0 & 3956810 \\ 0 & 50666 & 0 & 3956810 & 0 \\ 50666 & 0 & 3956810 & 0 & 335462666 \end{pmatrix} \qquad \mathbf{b}_{2} = \begin{pmatrix} 152789 \\ 102102 \\ 11921866 \\ 7964286 \\ 1010395474 \end{pmatrix}$$

(see http://www.fizyka.umk.pl/~tecumseh/EDU/MNII/inp)